#### ERASMUS+

EU programme for education, training, youth and sport

# Incoming student mobility

## Name of UNIOS University Unit: SCHOOL OF APPLIED MATHEMATICS AND **INFORMATICS**

### COURSES OFFERED IN FOREIGN LANGUAGE FOR ERASMUS+ INDIVIDUAL INCOMING STUDENTS

| Department or Chair within the UNIOS Unit | School of Applied Mathematics and Informatics  |
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| Study program                             | <ul> <li>Undergraduate university study programme in<br/>Mathematics and Computer Science</li> <li>Undergraduate university study programme in<br/>Mathematics</li> </ul>  |
| Study level                               | Undergraduate (Bachelor)   |
| Course title                              | Introduction to Control Theory with Applications   |
| Course code                               | M092   |
| Language of instruction                   | English  |
| Brief course description                  | <ul> <li>Syllabus.</li> <li>Introduction to dynamic systems. Linear time invariant (LTI) system.</li> <li>Control objectives. PID regulator. Implementation of PID regulator in discrete time model.</li> <li>Modelling and understanding control settings: example of differential drive wheel robot. Unicycle model.</li> <li>Linearization of nonlinear models.</li> <li>Asymptotic stability. State feedback (closed loop dynamics). Output feedback.</li> <li>Controllability and regulator synthesis by setting the desired eigenvalues (pole placement). Examples: Segway robot model and its controllability.</li> <li>Observability; The separation principle and regulator synthesis.</li> <li>Introduction to hybrid systems: Hybrid automata. Stability. Zeno behaviour in hybrid systems. Sliding Mode control and regularization.</li> </ul> |
| Form of teaching                          | Consultative teaching.   |

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| Form of assessment         | Classes are organized through lectures and exercises. During lectures<br>students will be familiarized with basic and important terms and<br>results in control theory. During exercises students apply the<br>acquired abstract knowledge to the concrete problems in mobile<br>robot control via MATLAB or Python based simulator, as well as<br>implement the theory on a real mobile robot (Raspberry Pi)<br>constructed by the students. Lectures and exercises are obligatory.<br>Exam will consist of a practical work (project) through which the<br>student has to demonstrate theoretical and practical skills learned.<br>Homework and seminar papers made during the semester will<br>influence the final grade. |
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| Number of ECTS             | 7  |
| Class hours per week       | 2+2+1  |
| Minimum number of students |  |
| Period of realization      | Summer semester  |
| Lecturer                   | Zoran Tomljanović  |